

Mat 241 Homework Set 3 – Due _____

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Directions: Show *all algebraic* steps neatly and concisely using *proper mathematical symbolism*. When graphs and technology are to be implemented, do so appropriately.

Mechanics:

#1. Determine the limit: $\lim_{t \rightarrow 1} \left\langle \frac{3}{t^2}, \frac{\ln t}{t^2 - 1}, e^t \sin\left(\frac{\pi}{3}t\right) \right\rangle$

#2. A particle travels along the path $\vec{r}(t) = \left\langle 2t, \frac{7}{2}t^2 \right\rangle$ $0 \leq t \leq \infty$ seconds.

A. On a separate graph hand sketch a trace of the vector function with $t = 0, 1, 2,$ and 4 seconds.

B. Determine the position vector and the unit tangent vector

$$\mathbf{T}(t) = \frac{\vec{r}'(t)}{\|\vec{r}'(t)\|} \text{ at } t = 1 \text{ second and hand draw both of these vectors}$$

on the graph in part B.

C. Eliminate the parameter, t , obtaining a function of the form $y=f(x)$ and hand graph this function over the domain $[0,4]$. Is this the same graph as in part A?

#3. Suppose that the velocity of a particle is modeled by the vector function

$$\vec{v}(t) = \left\langle \frac{2t^2}{16 - 3t^2}, te^{3t}, \sin^3(4t) \right\rangle. \text{ Find the position vector function } \vec{r}(t) \text{ and}$$

the acceleration vector function $\vec{a}(t)$.

#4. Suppose the trajectories of two objects are modeled by:

$$\vec{r}_1(t) = \langle t^2, 7t - 12, t^2 \rangle; \vec{r}_2(t) = \langle 4t - 3, t^2, 5t - 6 \rangle \quad t \geq 0$$

A. Determine if these particles ever collide.

B. If their paths do cross, how many times does it occur and when?

#5. Determine the *tangent line* to $\vec{r}(t) = \langle \sin(\pi e^t), \cos(\pi e^t), e^t \rangle$ at $t = 0$.

Concept Development & Graphics:

#6. Compute the tangent vectors and *unit* tangent vectors to the curves:

$$\bar{\mathbf{r}}(t) = \left\langle \cos t, \sin t, \frac{\sqrt{5}}{3} \right\rangle \quad \& \quad \bar{\mathbf{s}}(t) = \left\langle \cos t, \sin t, -\frac{\sqrt{5}}{3} \right\rangle$$

- A. Algebraically show that these two vectors form the intersection of the ellipsoid $\frac{4}{9}x^2 + \frac{4}{9}y^2 + z^2 = 1$ and the cylinder $x^2 + y^2 = 1$.**
- B. Use Maple or some other software package to graph the two surfaces on a grid (see helpful code). Make sure they are both on the same graph.**
- C. Compute the tangent vectors and *unit* tangent vectors to the curves. See page 858 example 1. Why do these two vectors have zero $\bar{\mathbf{k}}$ components?**
- D. What angular change in direction is measured by $T'(t)$ for both of these curves?**

#7. I claim that $T'(t) \perp T(t)$. Verify this result for the case when

$$\bar{\mathbf{r}}(t) = t^3 \bar{\mathbf{i}} + t^6 \bar{\mathbf{j}}$$

#8. There are several space curves that are quite interesting. Use a plotting software package like Maple to plot the 4 curves listed below.

A. Elliptical Helix: $2 \cos t \bar{\mathbf{i}} + 2 \sin t \bar{\mathbf{j}} + t \bar{\mathbf{k}}$

B. Conical Helix: $\bar{\mathbf{r}}(t) = \langle t \cos t, t \sin t, t^2 \rangle$

C. $\bar{\mathbf{r}}(t) = \langle \sin t, (1 - \cos t)^3, \sin(1 - \cos t) \rangle$

D. $\bar{\mathbf{r}}(t) = \langle t \sin t \cos t, t \sin^2 t, t \sin t \rangle$ let $0 \leq t \leq 8\pi$

To plot surfaces use this Maple code: Example:

A. Graph the following two surfaces: The ellipsoid: $\frac{x^2}{16} + \frac{y^2}{4} + \frac{z^2}{4} = 1$

and the cylinder: $x^2 + y^2 = 4$

B. Determine parametric equations for the space curve of intersection. Then plot the surfaces and the space curve of intersection on the same graph

Let $x = 2\cos(t)$ and $y = 2\sin(t) \rightarrow \text{note} : x^2 + y^2 = 4$

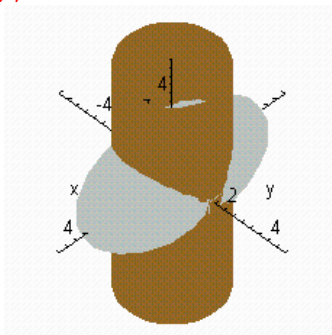
Using the above choice for x & y , find the $z(t)$ function(s) from the ellipsoid.

$$\frac{x^2}{16} + \frac{y^2}{4} + \frac{z^2}{4} = 1 \Leftrightarrow \frac{4\cos^2 t}{16} + \frac{4\sin^2 t}{4} + \frac{z^2}{4} = 1 \Leftrightarrow z^2 = 4 - \cos^2 t - 4\sin^2 t$$

$$\therefore z(t) = \sqrt{4 - \cos^2 t - 4\sin^2 t} \quad \text{and} \quad z(t) = -\sqrt{4 - \cos^2 t - 4\sin^2 t}$$

Solution to A.

```
> restart:with(plots):with(plottools):
Warning, the name changecoords has been redefined
Warning, the assigned name arrow now has a global binding
> a:=implicitplot3d(x^2/(16)+y^2/4+z^2/4=1, x=-5..5,y=-5..5,z=-5..5,numpoints=10000,color=gray,style = patchnograd):
> b:=implicitplot3d(x^2+y^2=4, x=-5..5,y=-5..5,z=-5..5,numpoints=10000,color=sienna,style=patchnograd):
> display(a,b,axes=normal);
```



Solution to B.

```
> c:=spacecurve([2*cos(t),2*sin(t), sqrt(4-(cos(t))^2-4*(sin(t))^2)],t=0..2*Pi,thickness=3,color=black):
> d:=spacecurve([2*cos(t),2*sin(t), -sqrt(4-(cos(t))^2-4*(sin(t))^2)],t=0..2*Pi,thickness=3,color=black):
> display(a,b,c,d,axes=normal);
```

